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	Filing Date		2001-06-14	
	First Named Inventor	Masanori Takano		
	Art Unit	2129		
	Examiner Name	Tran, Mai T.		
Attorney Docket Number		72785 SC162101		

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11	J. TONER et al., "Flocks, Herds, and Schools: A Quantitative Theory of Flocking," Physical Review E, The American Physical Society, Vol. 58, No. 4, October 1998, pp. 4828-4858.	<input type="checkbox"/>
12	J.I. NOUGARET et al., "Course-to-Fine Design of Feedback Controllers for Dynamic Locomotion," Visual Computer, Vol. 13, 1997, pp. 435-455.	<input type="checkbox"/>
13	D. BROGAN et al., "Group Behaviors for Systems with Significant Dynamics," Proceedings of the 1995 IEEE/RSJ International Conference on Intelligent Robots and Systems, 1995, Vol. 4, pp. 528-534.	<input type="checkbox"/>
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15	L. BROTMAN et al., "Motion Interpolation By Optimum Control," Proceedings of Siggraph 88, August 1988, pp. 309-315.	<input type="checkbox"/>
16	C.W. REYNOLDS, "Flocks, Herds, and Schools: A Distributed Behavioral Model," Siggraph 87, Computer Graphics, Vol. 21, No. 4, July 1987, pp. 25-34.	<input type="checkbox"/>
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18	X. TU et al., "Artificial Fishes: Physics, Locomotion, Perception, Behavior," Department of Computer Science, University of Toronto, (date unknown), pp. 1-8.	<input type="checkbox"/>
19	G. F. Franklin, et al., "Chapter 9: Multivariable and Optimal Control," Digital Control of Dynamic Systems, Addison-Wesley, Menlo Park, California, 1998, pp. 359-420.	<input type="checkbox"/>

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- ☒ Fee set forth in 37 CFR 1.17 (p) has been submitted herewith.
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A signature of the applicant or representative is required in accordance with CFR 1.33, 10.18. Please see CFR 1.4(d) for the form of the signature.

Signature	/Richard E. Wawrzyniak/	Date (YYYY-MM-DD)	2006-05-23
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